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**“Development of design variants
and mechanical construction of a
H2-scooter frame“**



- 1. Introduction**
2. Original State of the scooter
3. 2D Designs
4. 3D CAD Designs and CAE
5. Material for the 3D printing
6. FEM of the final frame
7. Additive Manufacturing-FDM
8. Printing Process
9. Other work and what is left to be done
- 10. Conclusion**



1. Introduction

Develop and manufacture a H2-scooter frame, which was dimensioned and optimized regarding the stress load.





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2. Original state of the scooter



Figure 1. Original Scooter

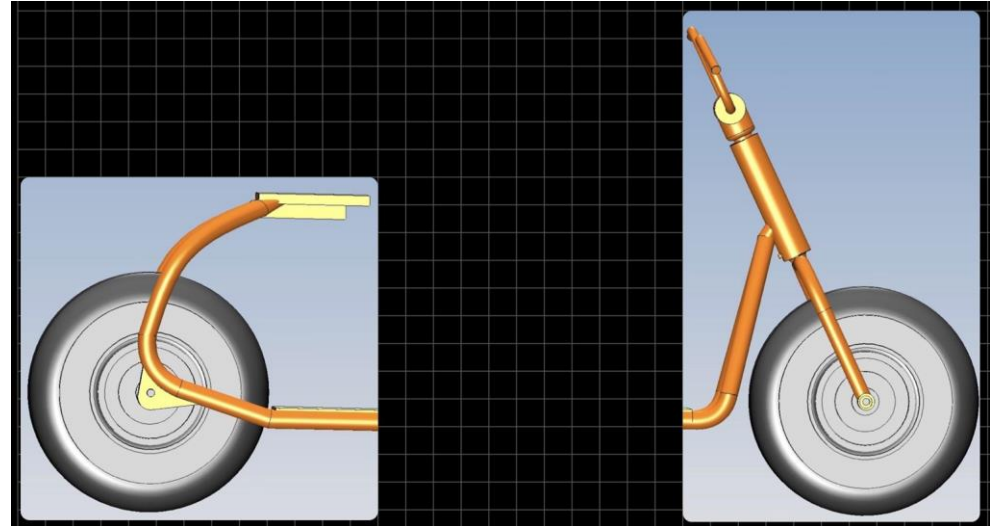


Figure 2. Cutted Scooter



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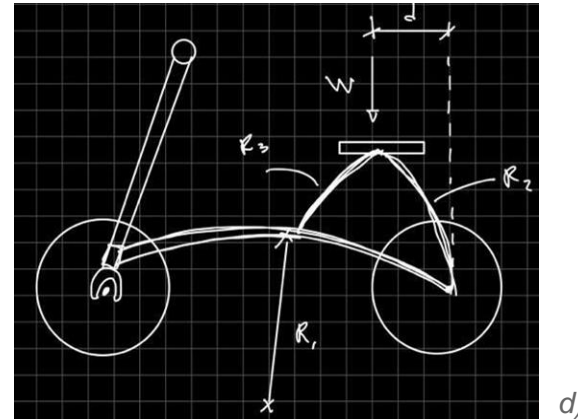
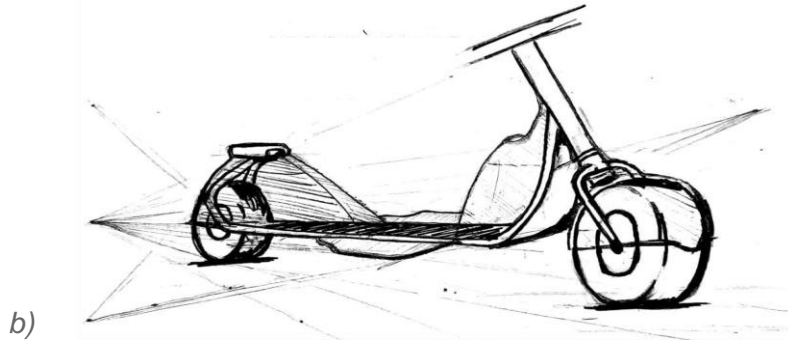
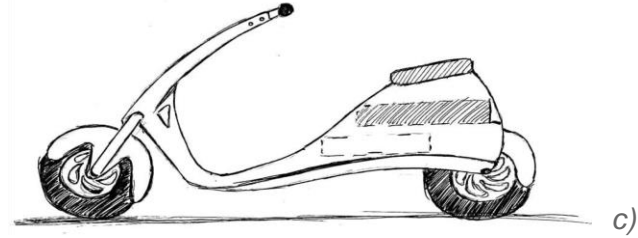
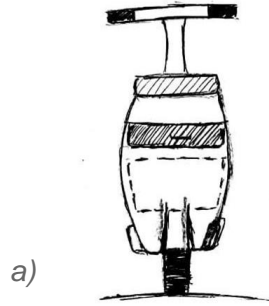
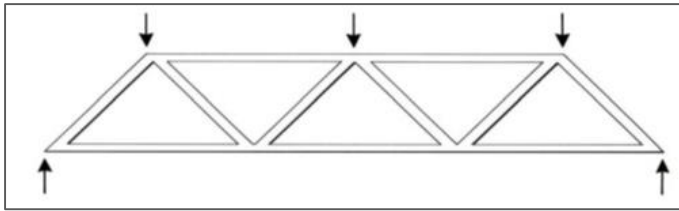
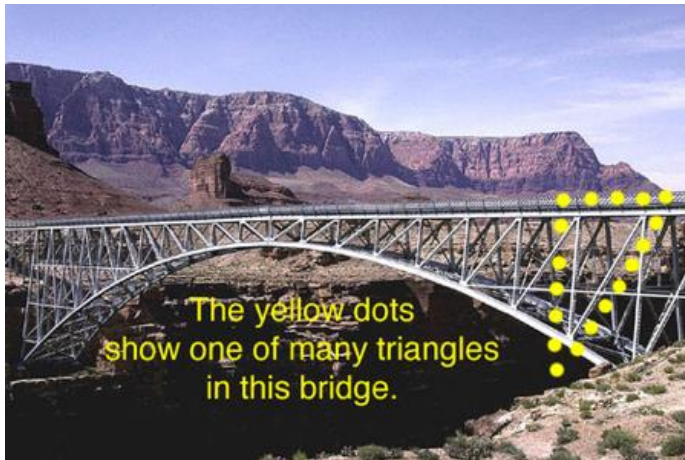


Figure 3. Sketches in images a) to d)



a)



b)



c)

Source:

<https://trianglesinbridges.weebly.com/why-triangles.html>

Figure 4. Examples of bridges in images a) to c)

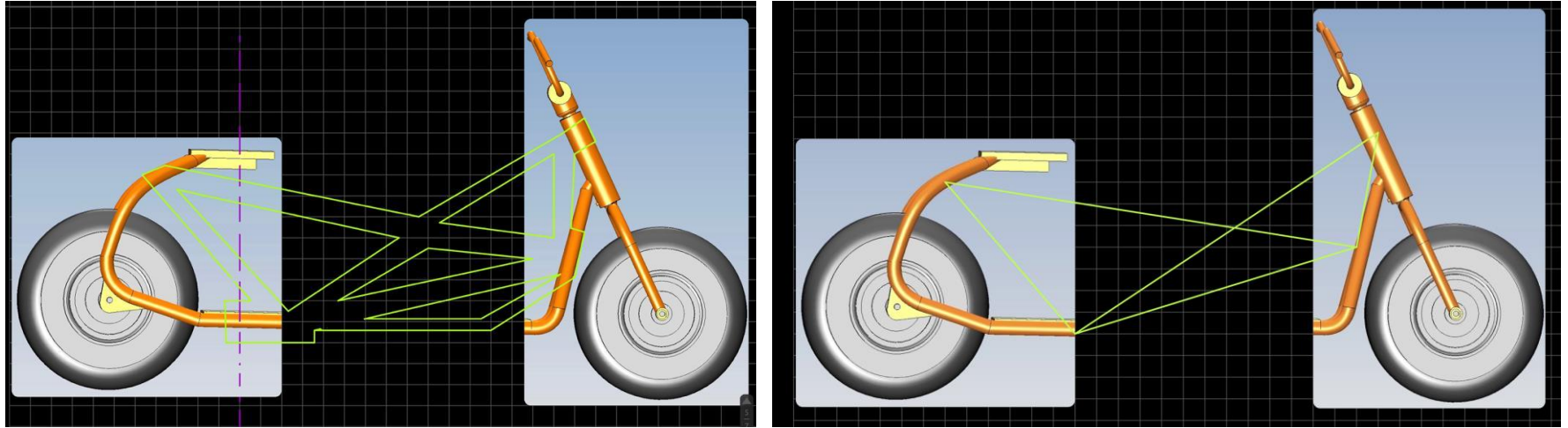


Figure 5. Structure design



Figure 6. Structure obtained

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4. CAD and CAE

- CAD
 - 2D or 3D product
 - Detailed diagrams of the materials
 - Tolerances
 - Dimensions of the product.
- CAE
 - Design
 - Virtual testing
 - Finite Element Analysis
 - Computational Fluid Dynamics,



Figure 7. Software used for the CAD and CAE

5. Original state of the scooter

- CAD Model of the original scooter frame
- Dimensions based on real measurements

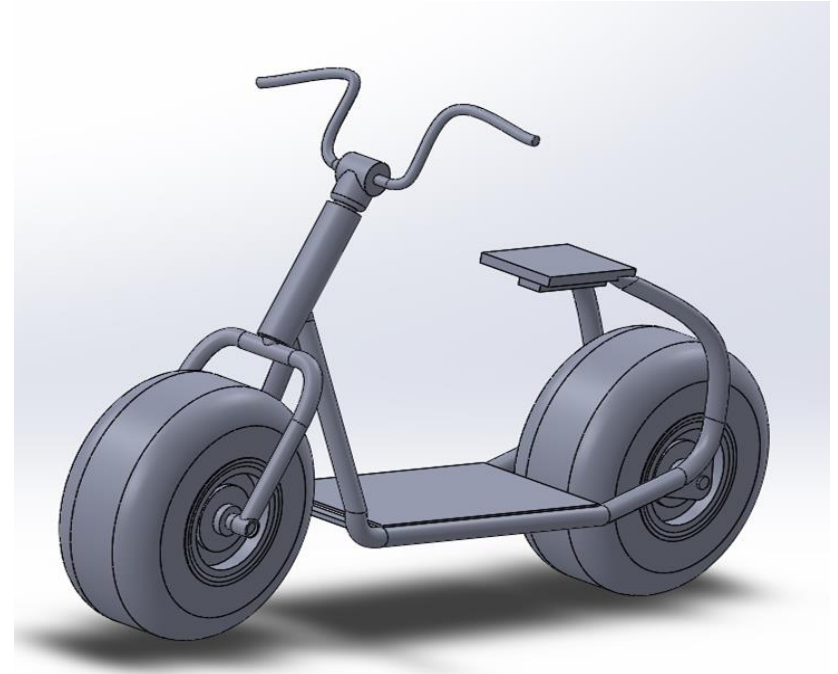


Figure 8. Isometric of the original scooter



Figure 9. Another view of the Frame CAD Model

- Complex geometry
 - Curves
 - Angles



Figure 10. Lateral view of the 1st Frame CAD Model

- 2D Design Proposal now implemented as a 3D CAD Model
- Blue part represents the proposed frame
- Silver part represents the metallic frame

- Triangles are the base of the frame structure
- Joints are hollow tubes



Figure 11. Isometric view of the 1st Frame CAD Model



Figure 12. Isometric view of the 2nd Frame CAD Model

- Metallic frame was redesigned
- A metallic box is implemented into the metallic frame

- 4 tubes are located in front part of the box for joining the plastic frame
- The box will carry the electrical components



Figure 13. Left view of the 2nd Frame CAD Model

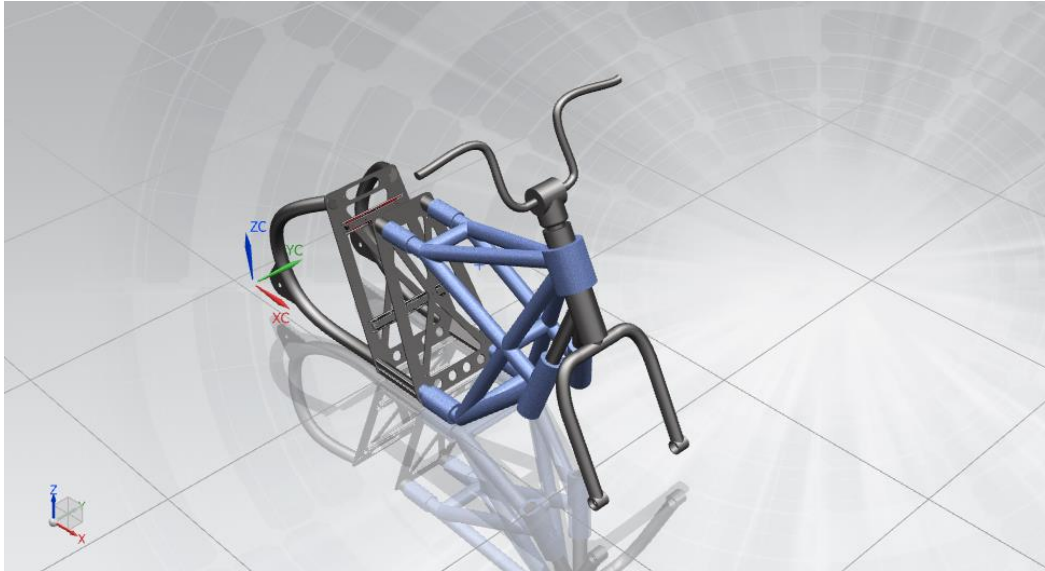


Figure 14. Isometric view of the 2nd Frame CAD Model

- Second 3D CAD Model proposal
- Blue part represents the proposed frame
- Gray part represents the metallic frame



Figure 15. Comparison of models



- Assembly of the scooter using the 2nd 3D CAD Model of the frame
- Electrical components are mounted in the metal box.
- Battery (green box) is placed in front of the box

Figure 16. Isometric view of the scooter assembly using 2nd Frame CAD Model

- Final assembly of the scooter
- Electrical components are placed in the metal box.
- Battery is placed in the inclined part of the frame



Figure 17. Right view of the latest scooter assembly

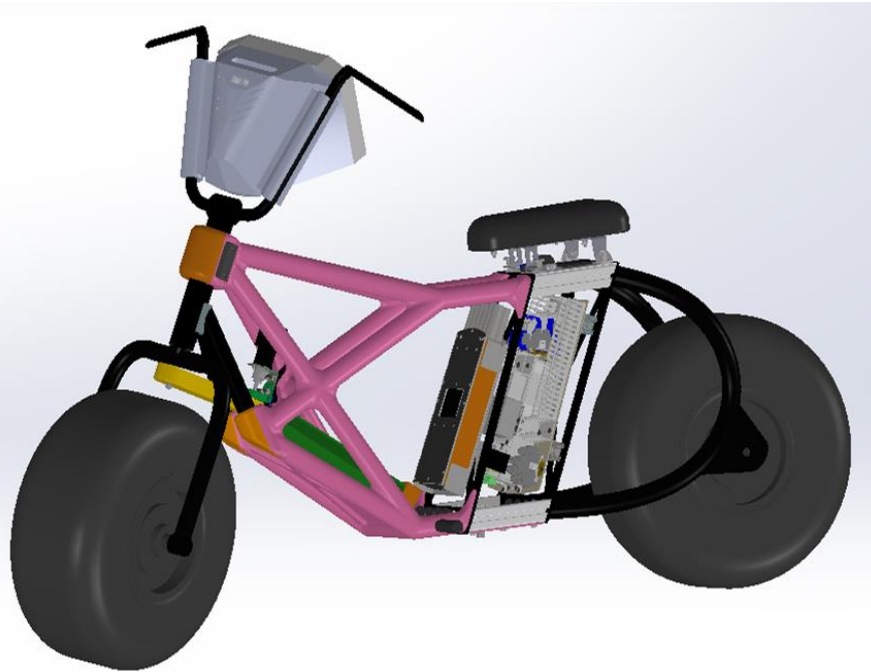


Figure 18. Isometric view of the latest scooter assembly

- Case for control module is attached to the steering wheel
- Mechanism for autonomous driving is implemented to the plastic frame and steering wheel

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Material to be used to print the e-scooter: ABS-M30

Tensile Strength, Yield: 26 MPa

Flexural Strength: 48 MPa

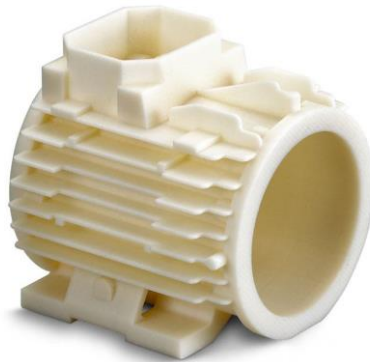


Figure 19. Example of the use of ABS-M30



Figure 20. Example of the use of black ABS-M30

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8. FEM of the final Frame

- Approximate solution of differential equations of the behavior of a system
- The divisions in the mesh are important.

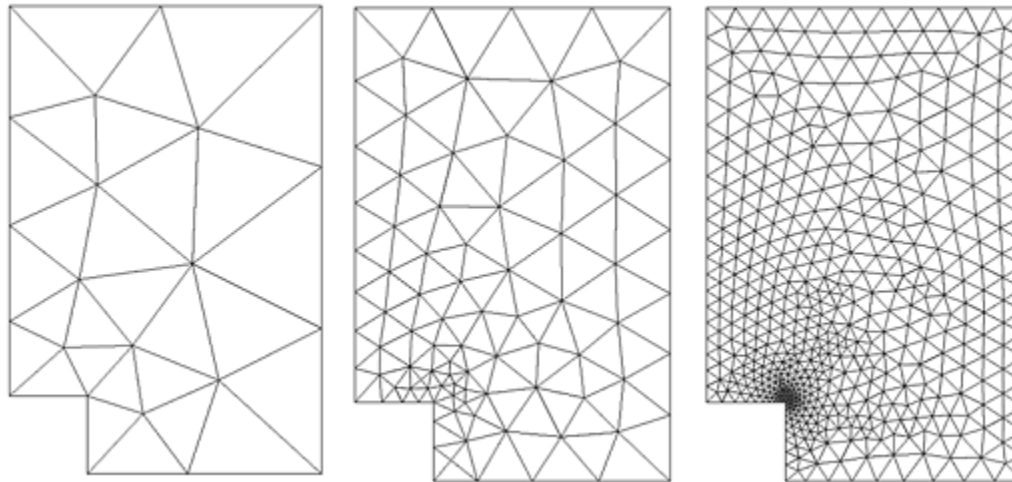


Figure 21. Thick, medium and fine mesh

8. FEM of the final Frame

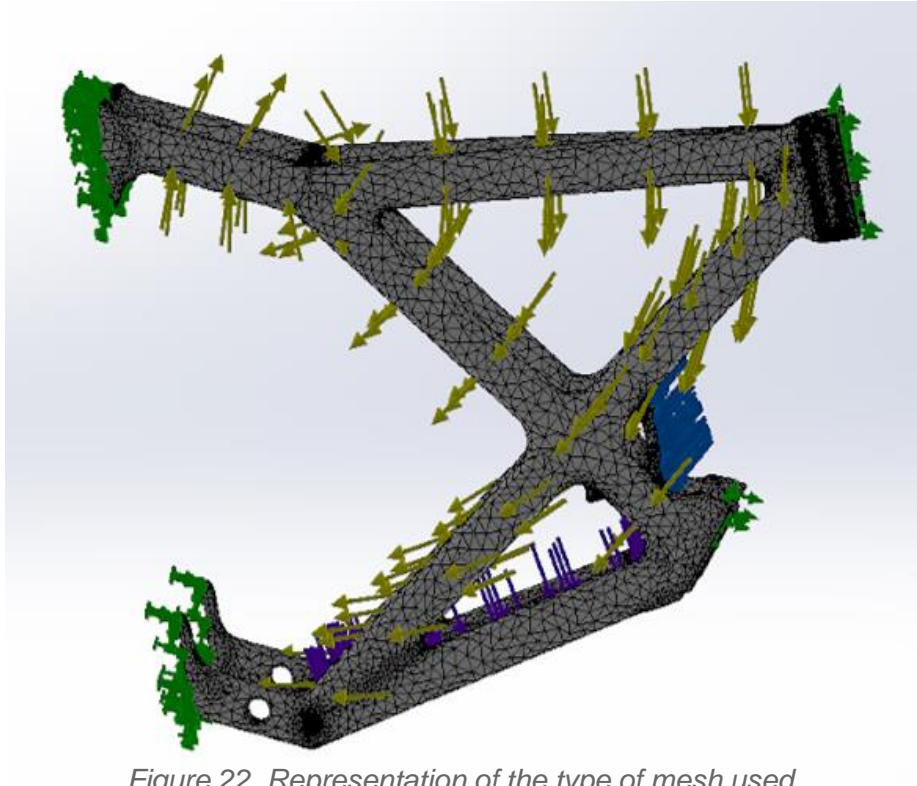


Figure 22. Representation of the type of mesh used

Medium/Fine Mesh

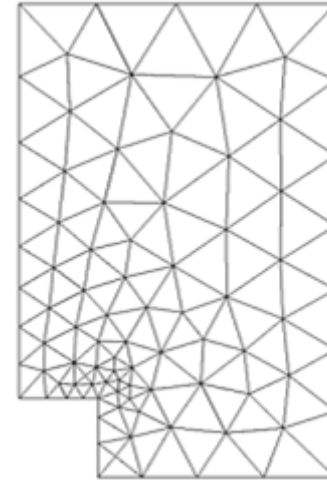
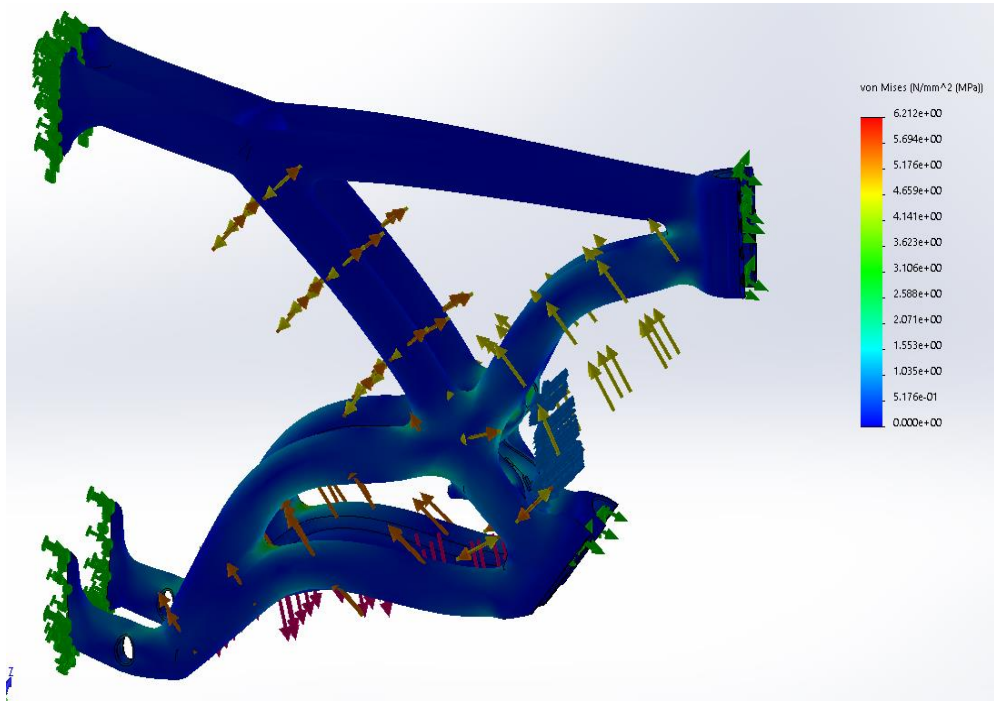


Figure 23. Medium mesh



Material

26 MPa Tensile Strength

48 MPa Flexural Strength

Maximum in Frame

6.2MPa Tensile Strength

Security factor: 4.2

Figure 24. Representation of the strength

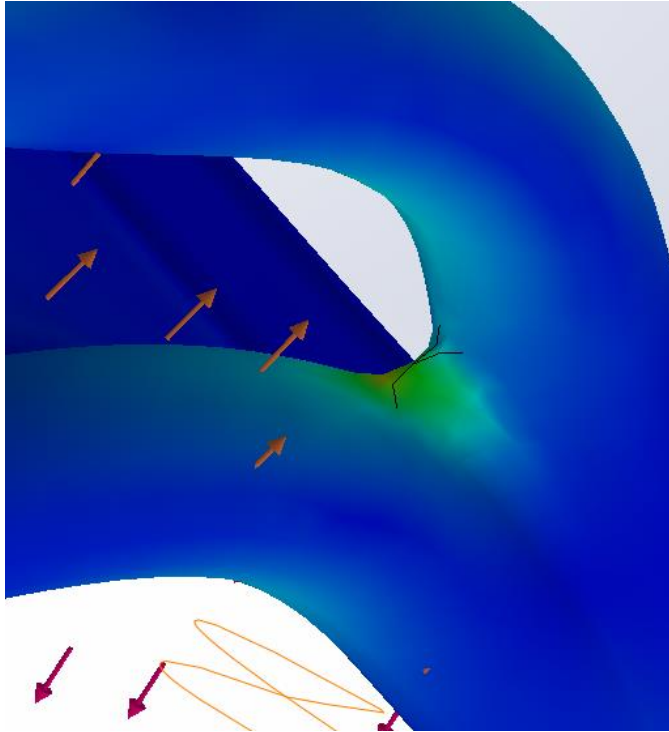


Figure 25. Representation of the maximum strength

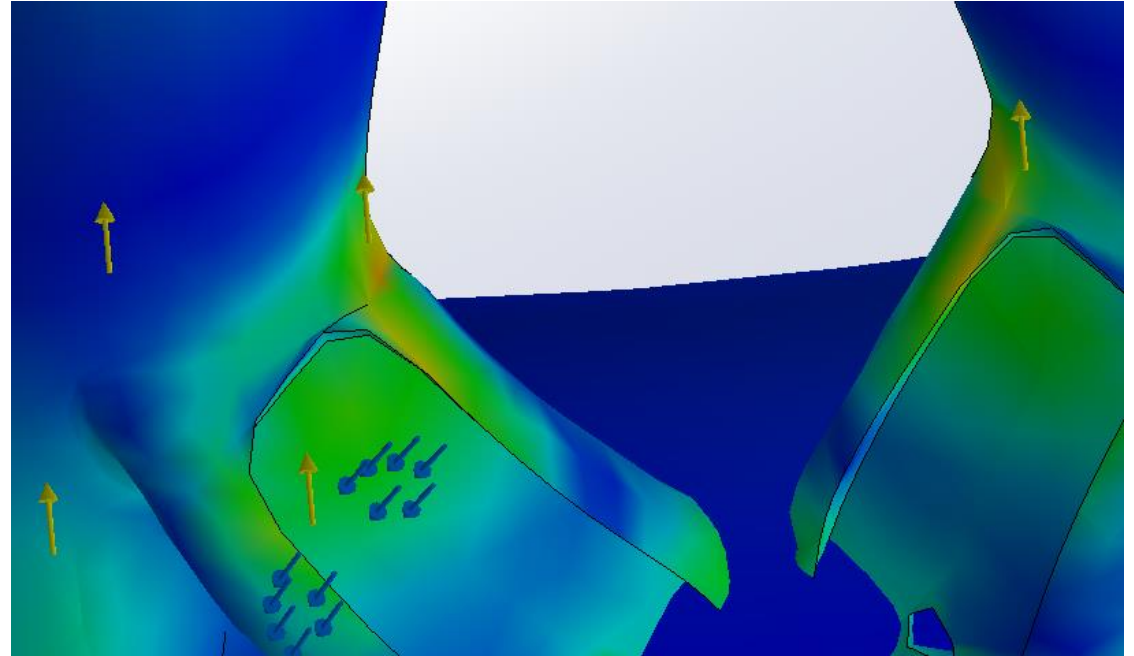
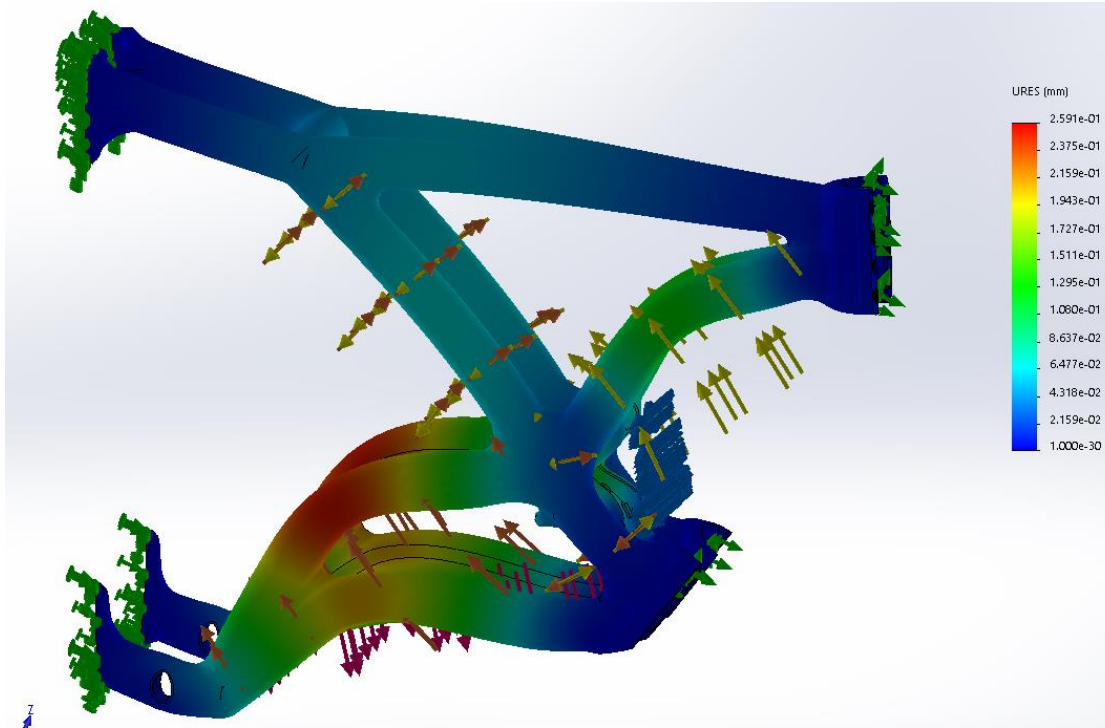


Figure 26. Representation of the maximum strength (zoom)



Maximum
displacement on the
frame: 0.3 mm

Figure 27. Representation of the type of mesh used

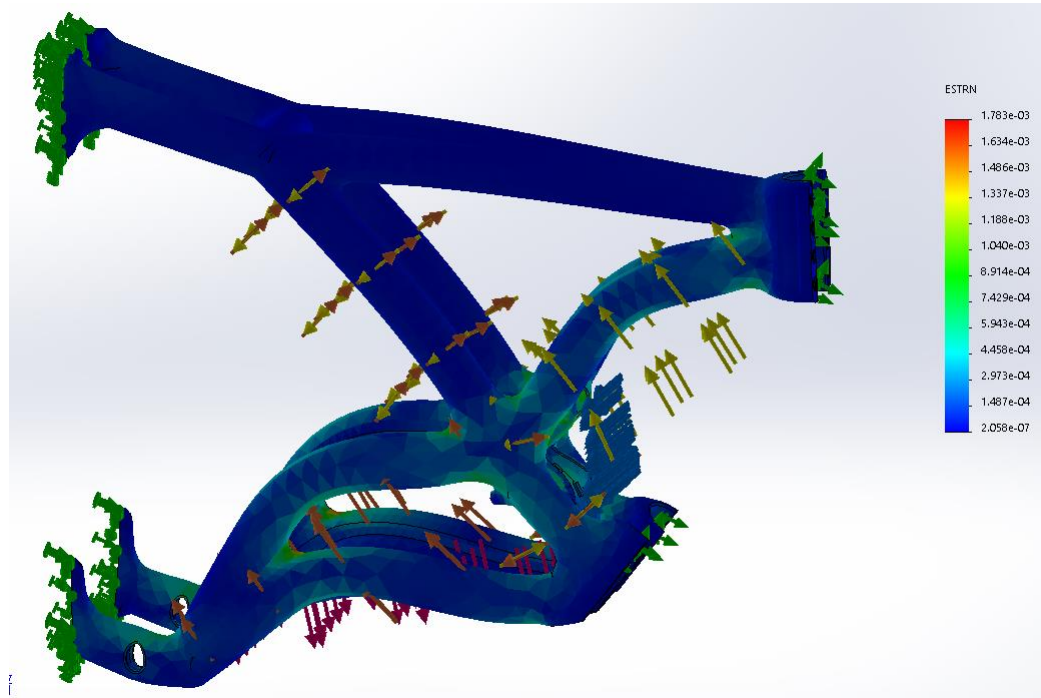


Figure 28. Representation of the type of the used mesh

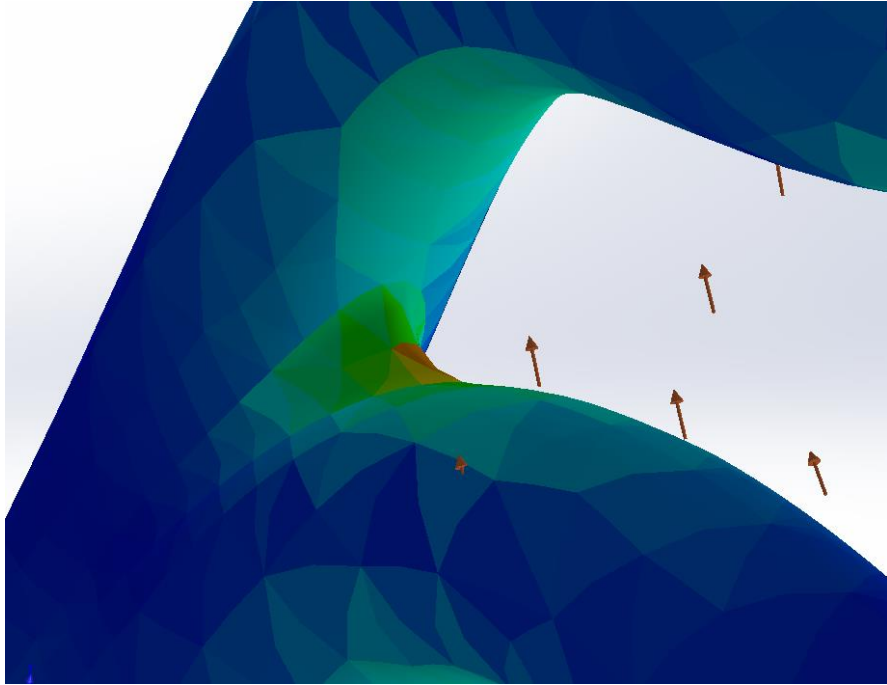


Figure 29. Representation of the maximum strain

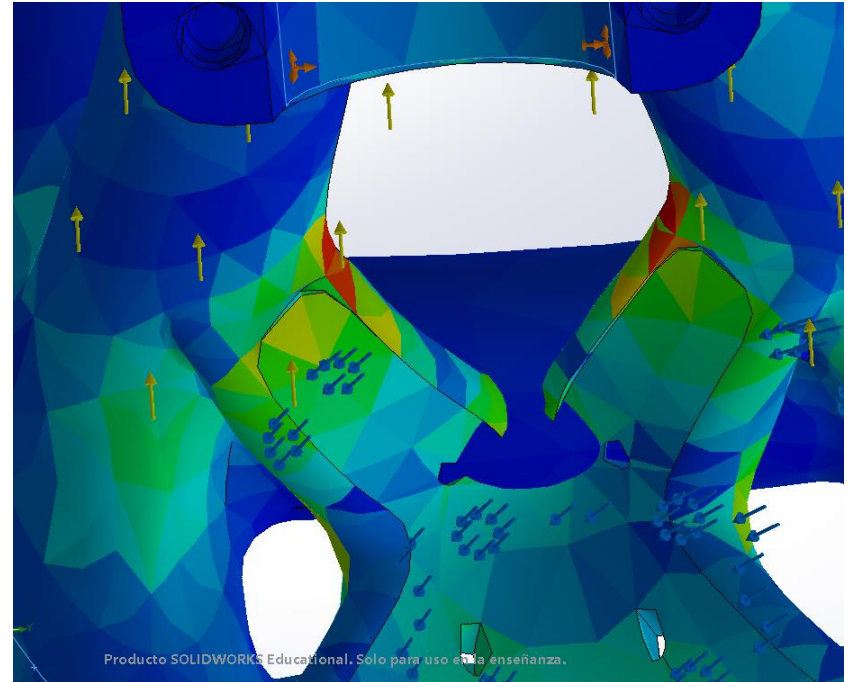


Figure 30. Representation of the maximum strain (zoom)

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- Joint of materials to make objects from 3D model data (3D-Printing)
- Object built one layer at a time

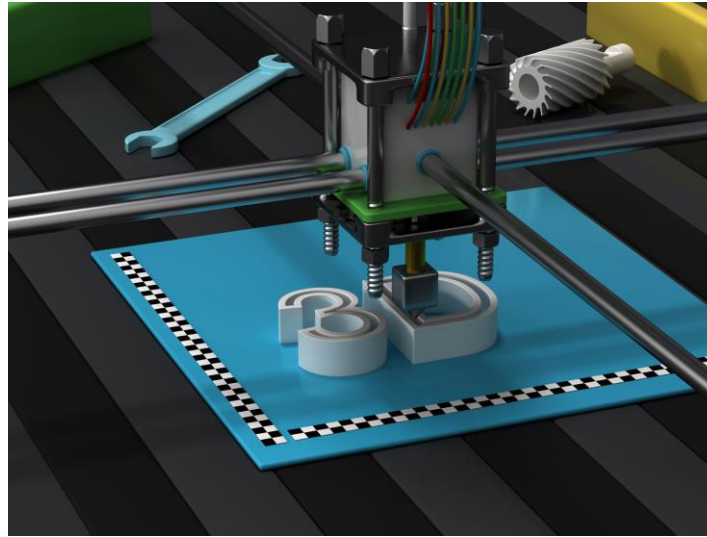


Figure 31. Additive manufacturing example



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8. Printing Process

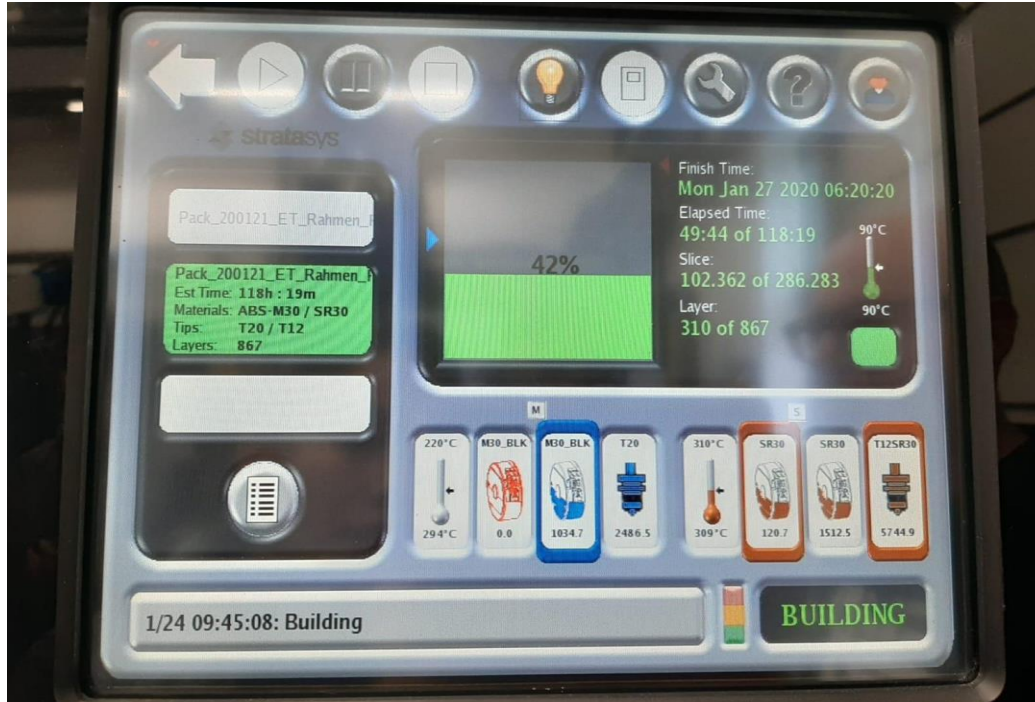
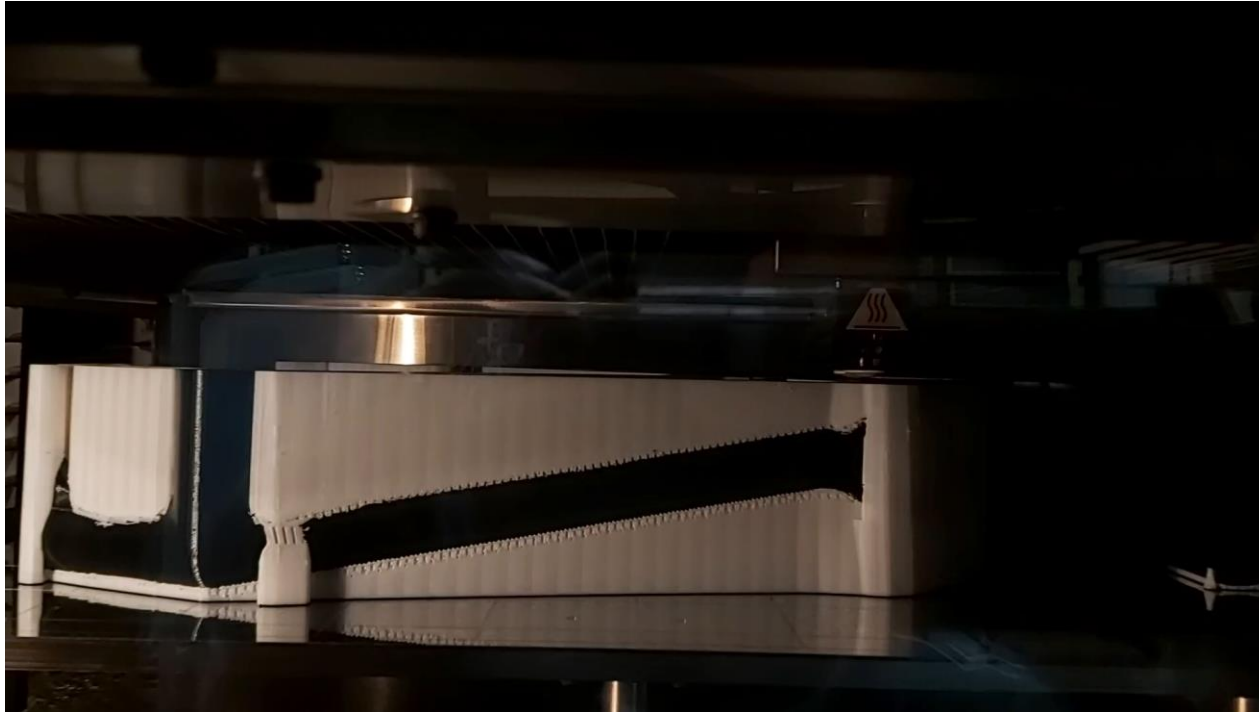


Figure 32. Screen of the 3D printer

- The used 3D printing process was FDM- Fused Deposition Modeling

8. Printing Process



Printing Process

8. Printing Process

- Printed frame with supporting material (white part)
- Connector parts for the joints
- Piece to fix the battery



Figure 33. Printed frame and printed components

8. Printing Process



Figure 34. Printed frame

- Printed framed placed between the metal box and the steering wheel

8. Printing Process

- Connection piece to join the plastic frame with the metal one.
- Lego Type Connection



Figure 35. Printed Lego Connector

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9. Other work and what is left to be done



Cut of unnecessary parts



9. Other work and what is left to be done



Figure 36. Previsualization of the assembly with the cuts done



Figure 37. Previsualization of the assembly with battery

- Unnecessary parts were cut.
- The battery was positioned.

9. Other work and what is left to be done



*Figure 38. Down part where the
metal tubes should be weld*



*Figure 39. Upper part where the
metal tubes should be weld*

- Weld of metal tubes

9. Other work and what is left to be done



Figure 40. Modifications to have a successful union



Figure 41. Gap between printed and metal frame

- Modifications



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We indirectly demonstrated the impact that CAD engineering software has. If in this project we had not had a design software, the time that we had to have invested would be much greater, as well as the range of error, since everything would have been done by hand.

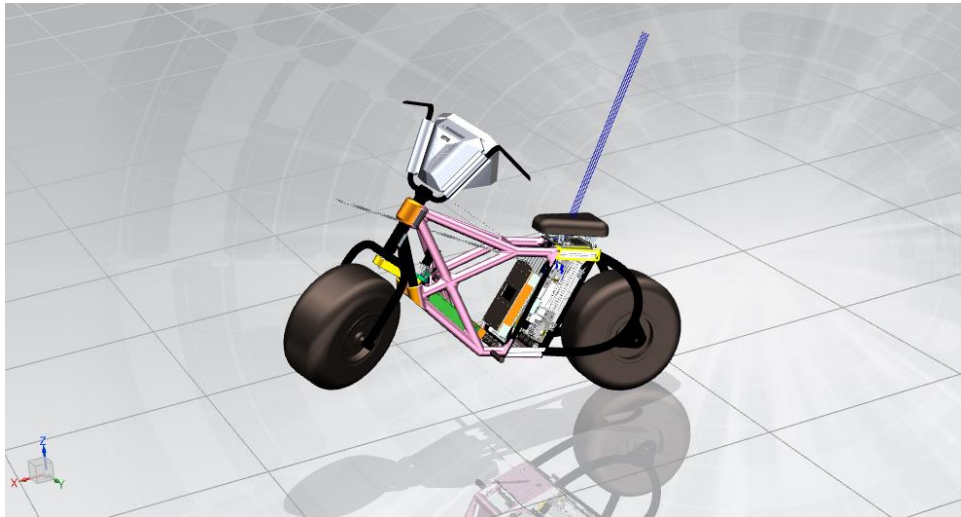


Figure 42. Render of the final frame



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